

USU AFOSR University Engineering Design Challenge Proposal

Steven Hansen
UTAH STATE UNIVERSITY

01/02/2015 Final Report

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FINAL PERFORMANCE REPORT FOR

GRANT FA9550-11-1-0326, "USU AFOSR University Engineering Design Challenge Proposal September 30, 2011 – September 29, 2014

Principal Investigator 2011-2012: J Steven Hansen, PhD

Principal Investigator 2012-2014: Byard D Wood, PhD, PE

ABSTRACT

Utah State University (USU) Mechanical and Aerospace Engineering (MAE) students participated in the 2012, 2013, and 2014 AFRL University Design Challenge. The USU teams took 1st place in 2012 and 2013 and 2nd place in 2014. AFRL selected a different design challenge each year. These winning designs were completed in MAE's senior level two semester capstone design course that includes the following design phases:

- First Semester: conceptual design, preliminary design, critical design review, design justification, drawing package.
- Second Semester: design fabrication, design testing and design evaluation.

The course is team taught by two faculty members who used the design approach used by NASA and by the Department of Defense. Each design team consisted of 7-14 students depending on the complexity of the design challenge.

INTRODUCTION

Based on its proposal to AFOSR in April 2011, Utah State University (USU) was selected to participate in the 2012, 2013, and 2014 AFRL University Design Challenge Program that included 16 universities from throughout the US plus three military academies. Each year AFRL selected a different real world challenge in its effort to help the Air Force solve critical problems. The three design challenges covered in this final performance report were:

Period of Performance	Design Challenge		
Academic Year (AY)	The intent of this project is to design a climbing assistance system for the		
2011-2012	typical warfighter without the use of a grappling hook. US troops that are		
	involved in various rescue and assault operations may be required to scale		
	vertical or near-vertical obstacles in high-risk, non-permissive environments.		
	The design of a system that allows scaling buildings or mountain faces under a		
	variety of conditions in an efficient and effective manner is the desired result.		
	The system should have the following characteristics:		
	 Ability to accommodate troops and their gear, approximately 300lbs 		
	 Capability to climb rock faces and concrete/adobe walls 		
	 The ability to ascend 60ft or taller surfaces that are vertical or near vertical. 		
	 The system should weigh less than 100 lbs and fit in a backpack and 		

carried by a single troop.

Academic Year 2012-2013

USAF Special Tactics Battlefield Airmen executing rescue and assault operations around the world have experienced difficulty traversing irrigation

canals, moving from one rooftop to another, crossing minefields, fast flowing mountain streams, snow and glacier crevasses, desert rock formations, unstable/collapsed structures, and compound walls. These obstacles typically range from one to twenty feet wide and have landings at different elevations.

Solutions to this problem should be light weight, have a multipurpose role (could be used for something other than a bridge), be easy to deploy (i.e. while wearing winter or tactical gloves), reusable, and easy to maintain (e.g. field repairable). It needs to be reliable, strong, and stable, so a soldier weighted down with gear or possibly carrying an injured person (i.e. total weight of 350 lbs) can safely traverse the obstacle.

Academic Year 2013-2014

The requirement is to lift building structures, aircraft, and armored vehicles ~45k lbs on uneven and sloping, wet, slippery, muddy, rocky, sandy (or a combination of) terrain to extricate equipment and personnel in situations where the scene is actively on fire or burnt and have exposed sharp metallic surfaces and oils and lubricants on the ground. The current constraint is the inability to make kits available in small enough volume and weight factor;

The system should have the following characteristics:

- Capable of being set up and employed rapidly
- Standoff controllable lift capability to increase/decrease load height
- Low operating pressure (if using a pneumatic solution)
- Operational in varying extreme cold/hot temperatures
- Operational at high altitude (minimum 10k MSL)
- Operational when exposed to various hazards such as aircraft/vehicle wreckage and must be able to withstand puncture/fire hazards during operation

USU APPROACH

USU's participation in the AFRL University Design Challenge was accomplished via the Mechanical and Aerospace Engineering (MAE) senior level capstone design course. The mechanical engineering BS curriculum includes a capstone design experience for all of its graduates. This two semester course includes the following design phases:

- First Semester: conceptual design, preliminary design, critical design review, design justification, drawing package.
- > Second Semester: design fabrication, design testing and design evaluation.

The course is team taught by two faculty members who have managed/supervised numerous RD&D design projects. Each design team consists of 6-14 students depending on the complexity of the design. Each team can select from a list of design challenges provide by the instructors. The design challenges are sponsored by companies, organizations, individuals, faculty research projects, and the MAE department.

All of the students have successfully passed all of the core mechanical engineering courses as a prerequisite for the capstone course. Each student will spend at least 200-300 labor hours over the two semesters.

The design approach that is taught in the MAE Capstone Design Course is the one used by NASA and by the Department of Defense. This approach is applicable to engineering or science driven hardware, software, and multidisciplinary design projects. There are six phases spread over two semesters with a

detailed design of a prototype being done the first semester and the building, testing and evaluating of the prototype being done the second semester. There is a strong emphasis on teams and working in teams.

The project phases include:

First Semester (Design phase)

- 1. The **Design Definition** (2 weeks)
- 2. The **Conceptual Design** with an informal review (2 weeks)
- 3. The **Preliminary Design** with a formal review and evaluation (4 weeks)
- 4. The **Detailed or Critical Design** with a formal review and evaluation (6 weeks)
 - Fill in all of the engineering details for the design to verify that it meets requirements
 - Develop detailed drawings
 - Deliverables:
 - i. Formal Critical Design Review
 - ii. Critical Design Review PowerPoint
 - iii. Formal written Design Report
 - iv. Complete drawing package

Second Semester (Build and test phase)

- 5. The **Manufacture and Building** of the prototype with a status review (7 weeks)
- 6. The **Performance Evaluation** with a formal final review and customer acceptance (7 weeks)
 - Test the prototype to verify that it meets the design requirements
 - Deliverables:
 - i. Testing report
 - ii. Prototype presentation and demonstration
 - iii. As-built drawing package

The AFRL Design challenge was assigned to two different teams. The teams were discouraged from talking with each other until after the critical design review. The intent was to create an internal design competition, since each team knew that only one design could represent the University at the completion.

ACCOMPLISHMENTS YEAR 1 (AY 2011-2012) - CLIMBING ASSISTANCE SYSTEM

As stated previously USU had two teams that independently developed a solution to the design challenge. However, USU decided to merge the two solutions into one solution. The result was that the USU team took first place in the competition. The following individuals were members of the wining team.



ASCENDING AGGIES (National Champions)

Row 1 L-R: Daniel Aguirre, Trevor Park, Mark Ortega, Bobby Johnson, James Robbins, and Alyssa Wahlin Row 2 L-R: Michael Deakin, Jordan Stott, Garrett Vaughan, Steven Daniels, TJ Morton, Tyson Burtenshaw, Rhet Astle, and Keith Bates

Row 3 LR Faculty Advisor Steve Hansen and Faculty Advisor Byard Wood Not Pictured: Vall Callisaya and Berk Demirgok

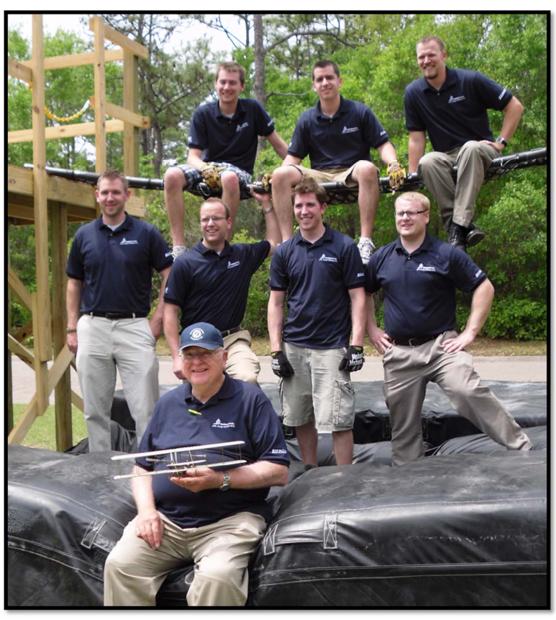
Their design presentation that was given to the AFRL Judging Panel is given in Appendix A.

ACCOMPLISHMENTS YEAR 2 (AY 2012-2013) - PORTABLE BRIDGE SYSTEMS

Two seven person teams (See team photos below) accepted the AFRL design challenge. Although A-Team was selected to represent USU at the competition, team Bifrost was allowed to present and demonstrate its solution. A-Team took first place in the competition. The design presentations are given in Appendix B.



A-TEAM (National Champions)
L-R: Taylor Clawson, Ben Scott, Tasha Davis, Mike Terry, Ruth Miller, Joe Woods, and Clair Hawkins Not pictured: Faculty Advisors Byard Wood and Dennis O'Hara



Team BIFROST

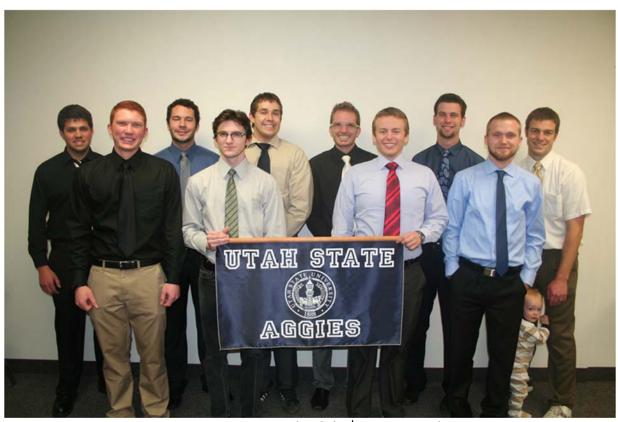
Top Row L-R: Andrew Ostler, Jens Rodman, and Preston Rich

Middle Row L-R: David Reynolds, Josh Vincent, Mitch Parker, Jeremy Kingsford

Bottom Row: Faculty Advisor Byard Wood Not Pictured: Faculty Advisor Dennis O'Hara

ACCOMPLISHMENTS YEAR 3 (AY 2013-2014) - LIFTING SYSTEM

Two ten person teams (See team photos below) accepted the AFRL design challenge. Although Aggie Life Lifters (ALL) was selected to represent USU at the competition, team All-Terrain Lifting Assistance System (ATLAS) was allowed to present and demonstrate its solution. ALL took second place in the competition. The design presentations are given in Appendix C.



AGGIE LIFE LIFTERS (ALL) (2nd Place Winner)

Front Row L-R: Nick Fluehe, Chris Donohue, Marcus Ritter, and Carson Holden Back Row L-R: Alex Bernkopf, Kyle Mattinson, Derek Shelley, Ryan Clawson, Roger Thorpe, and Hiram Knapp Not Pictured: Faculty Advisors Byard Wood and Daniel Magda



All-Terrain Lifting Assistance System (ATLAS)

Top Row L-R: Chase Crandall, Dallan Webb, Philip Le Goubin, Nathan Hawkes, and Logan Williams Bottom Row L-R: Jacob Singleton, Trevor Christensen, Joseph A. Landon, Andrew Gerber, Landon Nielsen Not Pictured: Faculty Advisors Byard Wood and Daniel Magda

CONCLUDING OBSERVATION

The AFRL University Design Challenge has provided engineering students with a "real world" design challenge that was exciting and meaningful to the Utah State University Mechanical and Aerospace Engineering senior level students. The principal author (Byard Wood) has been involved with student design competitions at three universities extending over three decades. In his opinion, the AFRL University Deign Challenge Program ranks as the very best design challenge for students in a capstone design course for three primary reasons: 1) unlike many of the students design competitions that have the same challenge year after year, a new challenge was given each year so that all teams started with a "clean slate" such that there was not a design legacy that needed improvements, 2) all teams were given the same budget, and 3) AFRL personnel were available throughout the design process to help clarify and provide feedback to the students.

APPENDIX A

ASCENDING AGGIES Student Design Presentation given to the AFRL Judges April 20, 2012



Team Picture



Design Challenge

How do we assist a team of four soldiers in climbing a 90 foot wall without a grapple hook?

3

Design Requirements & Goals

- Support 300 lbs
- Ascend 90+ ft surfaces
- Fit inside 3 cubic ft
- Stealth Desired
- Minimal weight desired

USU Solution

- Vacuum Ascender
- Adhesive Anchor
- Rope Ascender



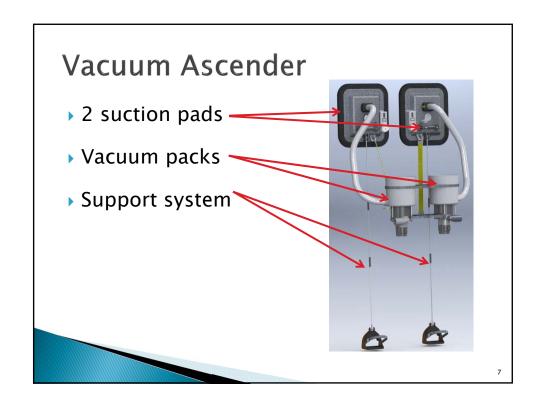




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University Design Challenge

- 1. Team member(s) ascends with vacuum ascender
- 2. At the top, the team member(s) applies adhesive anchors
- 3. Remaining team members ascend with rope ascenders



Suction Pads

- Base
 - Aluminum 6061-T6
- Pressure release
 - 2 in. diameter hole
- Instrument panel
 - Analog vacuum gauge, voltmeter, on/off switch
- Handle
 - Aluminum, 7.5 in. wide
- Skirt
 - EVA foam, abrasion resistant
- Friction strip
 Stealth Rubber





Vacuum Packs

- ▶ Hose
 - 1.5 in. diameter
- Wiring
 - 16 gauge
- Batteries
 - 5000 mAh and 1.49 lbs/battery
 - 7/vacuum pack
- Vacuum motor
 - 3-stage, 3.8 psi differential, 93 CFM, 6.1 lbs./motor



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Support System

- Connection Rod
 - 1300 lb tensile load
- Harness/Daisy chains -
 - 300lb. rating
- ▶ Foot Support
 - Stability and comfort



Testing

- Vacuum Ascender
 - Seal Test
 - Support System Test
 - Horizontal Surface Test
 - Motor Test
 - Battery Test
 - Wet Surface Test



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Improvements from Testing

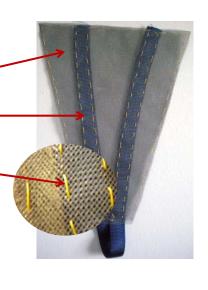
- ▶ Toe spikes
- Climbing Ladders
- Pressure Release





Adhesive Anchor

- Special T CA Glue
- Fiberglass Mesh-
- Nylon Webbing
- Grade 49 Kevlar Thread



13

Adhesive Anchor (2)

- Tested to hold at least 360 lbs.
- Shear Strength870.2 psi 2901 psi





▶ 1/8 in. Technora rope

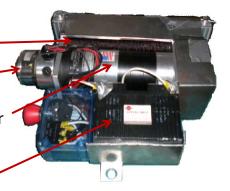
Winch style

Brake Feature

▶ 609 in. lbs. gear motor

Fully Reversible

Battery powered



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Rope Ascender (2)

- ▶ Tested to 300 lbs
- Tested battery life
 - Ascended equivalent of 300 ft.
- Tested rope to withstand wear of climbing



Safety Features

- Vacuum Ascender

Vacuum gauge

- Voltmeter
- Recessed on/off switch
- Harness/daisy chains

- Rope Ascender
 - Reversible
 - Emergency stop button to engage brake

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Design Meets the Requirements

- Supports over 300 lbs
- Ascends 90+ ft surfaces
- Fits inside 3 cubic ft
- Stealth achieved in glue pad and rope ascender
- Minimal weight desired, with an overall solution weight of 132 lbs
 - 33 lbs per soldier (4 soldiers)

Concept of Operations

3 Steps:

- 1.Team member(s) ascend the wall
- 2.Team member(s) attaches glue pads
- 3. Remaining team members simultaneously ascend

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Climbing a Brick Wall



APPENDIX B

CROSSING THE GAP

A-Team

Break-Apart Mobile Bridging and Infiltration (BAMBI) Device

And

CROSSING THE GAP BIFROST

Obstacle Crossing Device (OCD)

Student Design Presentations given to the AFRL Judges
April 17, 2013

Crossing the Gap

Break-Apart Mobile Bridging and Infiltration (BAMBI) Device

Utah State University The A-team

Clair Hawkins Taylor Clawson Ruth Miller Ben Scott Tasha Stembridge Michael Terry Joe Woods







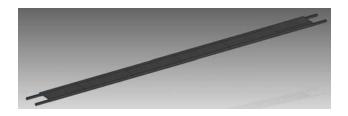
Design Purpose

Enable USAF Airmen to traverse obstacles such as canals, fast flowing mountain streams, glacier crevasses, desert rock formations, and collapsed structures

Able to quickly assemble and deploy

Usable in every climate condition, day or night





Design Objectives

Span obstacles of 5 to 20 feet

Under 20 lb.

Hold a 350 lb. static load

Packed volume under 5 ft³

Multipurpose - perform at least 2 functions



3

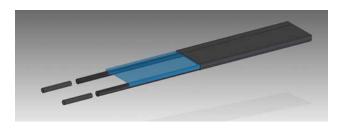


Design Solution BAMBI

6 sections, each 44 in. long
Walking platform 14 in. wide
Sections secured with Velcro
Ends wrapped in Kevlar and
rubber for traction and
protection

Textured surface for traction





Section Construction

Joint tubes attached with urethane resin

Main tubes epoxied to foam platforms

Foam and main tubes wrapped in carbon fiber weave

Velcro adhered to the bottom side of the bridge



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Joints

High modulus carbon fiber

12 in. long

1.6 in. outer diameter

Twice as thick as main tubes (0.11 in.)

Set of joints yields at a moment greater than 1750 lb.-ft.



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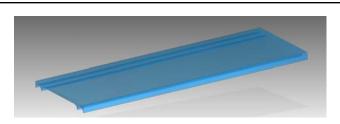


Main Tubes

High modulus carbon fiber
44 in. long
1.75 in. outer diameter
Thickness varies between 0.07
and 0.08 in.
Ends are reinforced with extra
hoop layers



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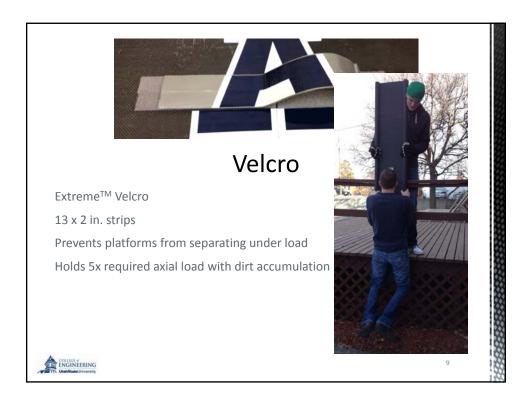
Platform

44 in. long and 14 in. wide

STYROFOAM™ brand Hi-Load 40 foam board

CNC used to shape foam for precise fit







Feet

Ends wrapped in Kevlar & encased in rubber

Protects from impact and sharp objects

Provides traction on various surfaces

COLLIGI V ENGINEERING



Walking Surface

Sand bonded to carbon fiber with epoxy for strengthened bond

Chevron pattern

Adds traction in inclement weather

Allows use on steep inclines





1:



Portability

Can be strapped to any backpack
Weight can be dispersed among
multiple users

Platforms don't require protective covering





Can be used to climb structures up to 15 ft. high Self leveling on mildly uneven surfaces Usable as a stretcher Extra Features



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Component Design Requirement Actual Failure Point Main tube Withstands a moment of at least 875 lb.-ft. 1031 lb.-ft. Joint Withstands a moment of at least 1750 lb.-ft. 2042 lb.-ft. Velcro Holds an axial load of at least 40 lbs. Greater than 200 lbs.

Component Testing Results





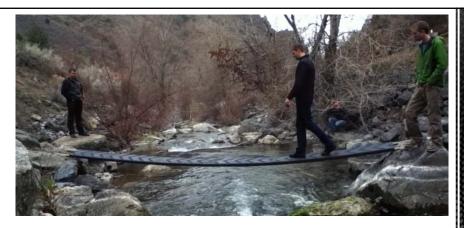
Deflection Testing

Total deflection of 14 in. with a 350 lb. central load

Deflection caused primarily by tolerances in joints

COLLIGI - ENGINEERING





Total Weight 27.2 lbs.

Packed Volume 3.95 ft³

Variable Span up to 20 ft.

Easy to use

Short deployment and retrieval time



1/

BAMBI

Summary

Cost Analysis

Research and Development Costs

Total Hours		~1400
14-Jan Texas Almet	Aluminum honeycomb	\$334.12
17-Jan Rockwest Composites	2.625" CF tubing	\$448.59
29-Jan Reliable Source	36" aluminum tubing	\$545.00
23-Jan IPACO	Steel for jig	\$23.37
24-Jan IPACO	U-bolts	\$14.92
7-Mar Strapworks.com	Aluminum buckles	\$19.37

Subtotal \$1,385.37

Material Costs

28-Jan Alumilite	Rubber	\$171.30
22-Feb TMI	Epoxy	\$107.82
19-Feb Home Depot	Foam board, acetone	\$41.68
23-Feb Home Depot	Sandpaper, lumber, paint liner	\$51.87
4-Mar HD Supply White Cap	Foam board	\$188.24
7-Mar TMI	Ероху	\$115.21
26-Mar Archeo-Tectura	Foam CNC	\$470.00
Toray	M40j	\$1,261.00
Ben Scott	Travel to Northfork	\$576.00
Lowes	Layup supplies	\$108.51
23-Mar Home Depot	Velcro	\$62.24
1-Apr Home Depot	Vacuum tape	\$5.23
2-Apr Home Depot	Duct tape, painter tape	\$24.11
Subtotal		\$3,183.21

COLUGI & ENGINEERING

Weight and Volume Breakdown

Weight Summary

Total	12350	27.
Section 6 (End)	1869	4.
Section 5	2071	4.
Section 4 (Thick Joints)	2133	4.
Section 3 (Thick Joints)	2105	4.
Section 2	2065	4.
Section 1 (End)	2108	4.
	Weight(g) We	eight (lb)

Packed Dimensions

Volume (ft³)	3.9
Height (in)	9.2
Width (in)	16.
Length (in)	44.7

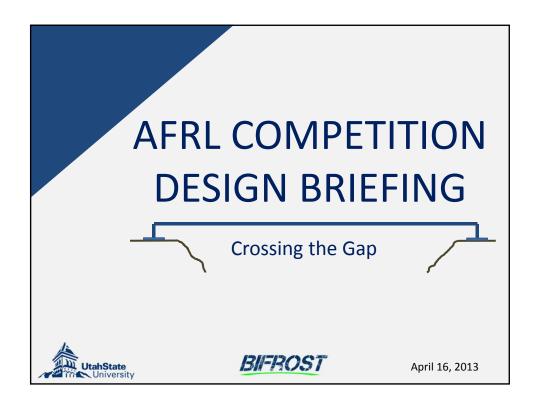


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Optimize feet for lower weight T1000 carbon fiber Optimize foam thickness

Manufacturing technique

Future Improvements



Design Objective

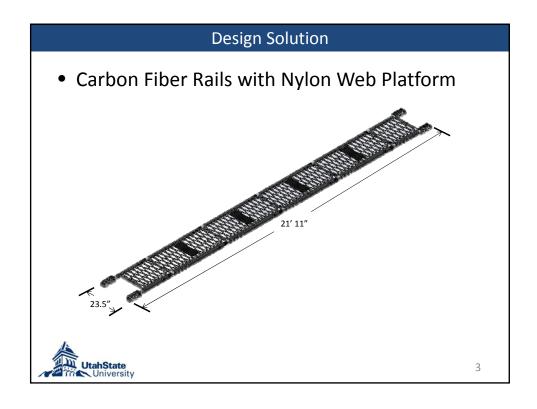
• Create a system to safely transport multiple USAF Airmen across various obstacles.

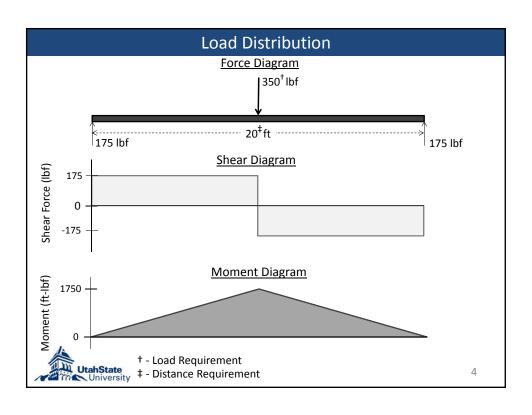
Gap Length: Up to 20 feetMaximum Load: 350 lbs.

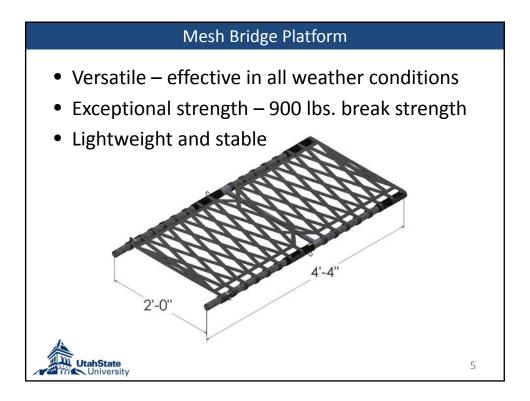
Surface Conditions: Vary with Terrain

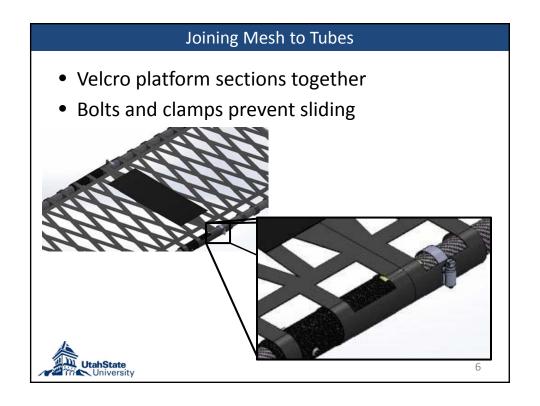












Footing





- Designed to function on multiple surfaces
- Lightweight aluminum
- Universal attachment



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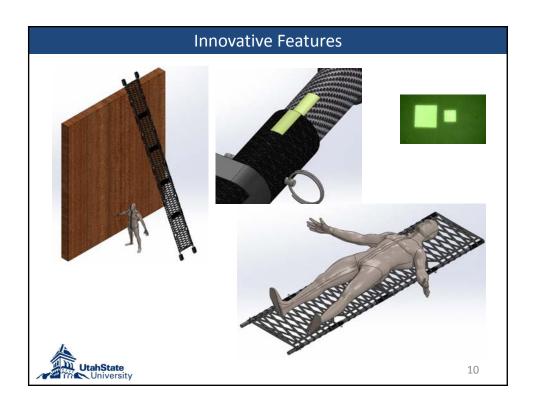
Size When Packed

- Total Volume (3 packs): approx. 2.7 ft³
- One pack contains: Two 4' sections, mesh and one tension bar
- Pack Dimensions: 11" X 5" X 24"









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Costs		
Cost/Unit	Qty	Total Cost
\$23.29/ft	40 ft	\$950
\$26.76/ft	12 ft	\$330
\$0.33/ft	500 ft	\$115
\$125 ea	4	\$500
\$4 ea	40	\$160
\$75 ea	5	\$375
		\$300
		\$2500
		\$5280
	\$23.29/ft \$26.76/ft \$0.33/ft \$125 ea \$4 ea	Cost/Unit Qty \$23.29/ft 40 ft \$26.76/ft 12 ft \$0.33/ft 500 ft \$125 ea 4 \$4 ea 40

UtahState University

UtahState University

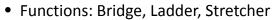
Weights			
Item	Weight/Unit	Qty	Total Weight
Composite Tubing (Main)	0.4 lb/ft	40 ft	17 lb
Composite Tubing (Sleeves)	0.5 lb/ft	12 ft	7 lb
Mesh	0.0088 lb/ft	500 ft	7.4 lb
Footing	1.25 lb	4	5 lb
Pins	0.01 lb	40	1.4 lb
Tensioners	0.75 lb	3	3.4 lb
Total Weight			41.2 lb

Summary



Gap Length: 4 to 20 feetWeight of system: 41.2 lbs.

• Packed Volume: 2.7 ft³



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Phase II System Advancements

- Improve system connections for increased speed
- Test other carbon fiber layups in order to reduce tube diameter and weight



UtahState University

Questions?



APPENDIX C

HYDRAULIC LIFTING SYSTEM Aggie Life Lifters

And

ALL-TERRAIN LIFT ASSISTANCE SYSTEM Aggies that Lift Armored Vehicles

Student Design Presentations given to the AFRL Judges
April 16, 2014





Design Objective

Create a system to safely rescue an injured person pinned under an armored vehicle

○ Vehicle weight: 45,000 lbs.

™ Lift Height: 18 to 24 inches

○ Packed size: 12" x 12" x 6"

Environment





Aggie Life Lifters

Design Solution



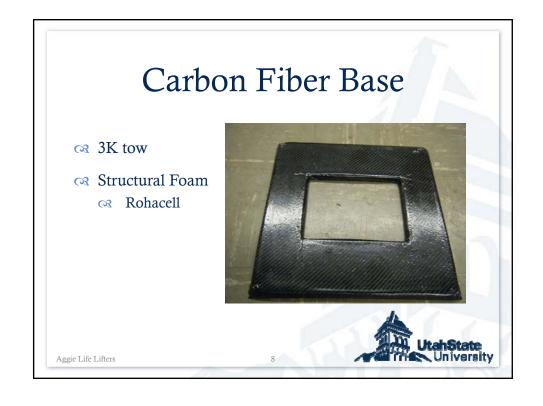
Aggie Life Lifters

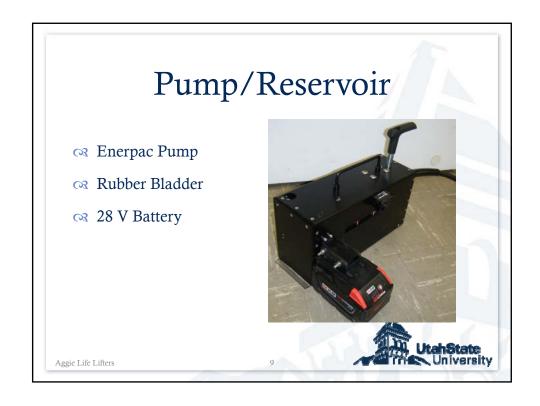






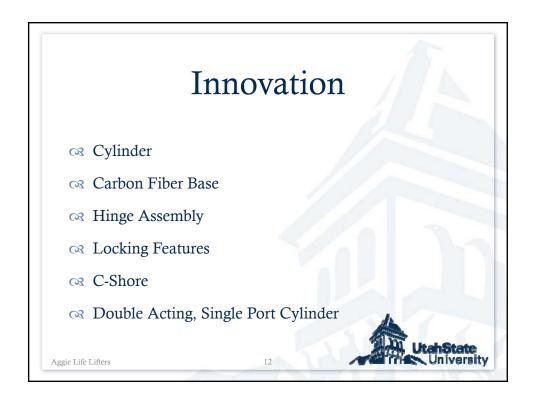


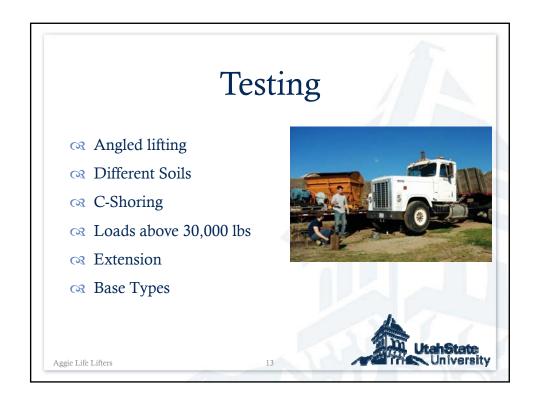




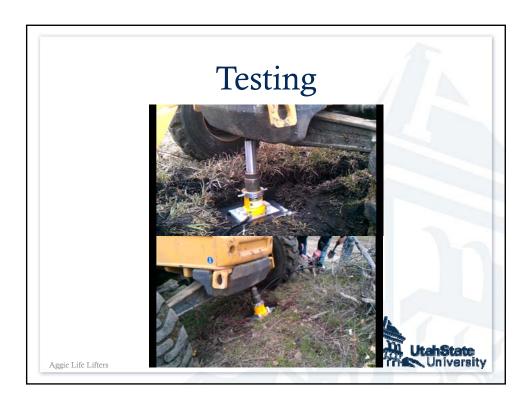












		Parts List	
	Component	Weight [lbs]	Cost [\$]
	Base	1.45	176
	Hydraulic Cylinder	16.5	2000* Donated for project
	C-Shore	3.5	100*
	Extension	1.85	200*
	Pump/Reservoir	18.8	2670
	Hoses	1.85	100
	Base Assembly	4.93	700*
	Battery	1.5	125
	Saddles	1.95	214
	Shovel	1.3	13
	Total	53.63	6,298
ie Life Lifters		* Estimated cos	UtahSta

Future Improvements

- Different Materials for the Cylinder
- Rotentially Eliminate Base Rotation Feature

- Remote Control for Hydraulic Pump

Utah State University

Aggie Life Lifters

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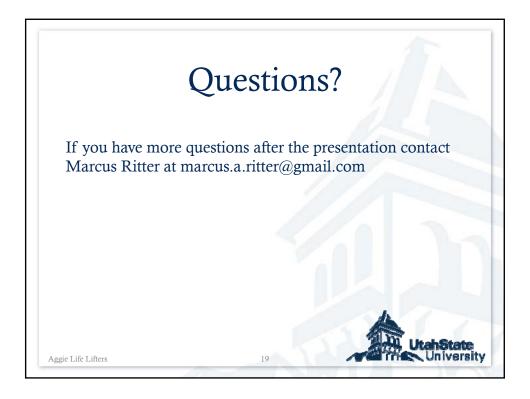
Summary

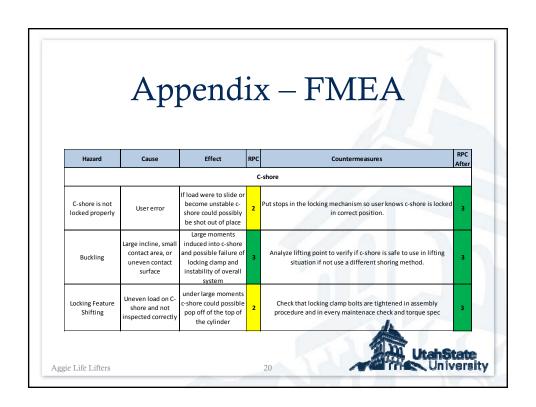
Parameter	Requirement	ALL*	Margin 1**
Lift Height	18"	22"	18%
Max Load	45,000 lbs	45,000 lbs	0%
System Weight	<30 lbs	53.63 lbs	-78.7%
Packed Dimensions	12x12x6"	14x14x7"	-58.8%
Operating Pressure	<150 PSI	N/A	

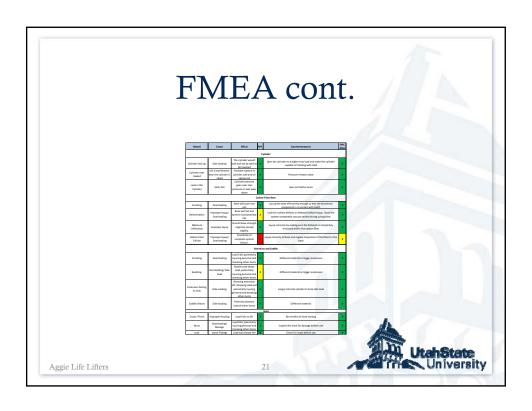
*Current Best Estimate

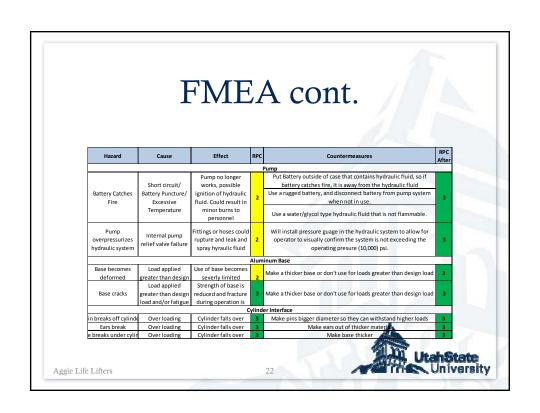
**Margin%= [Requirement-Specification]/Requirement*100

Aggie Life Lifters















All-Terrain Lift Assistance System "ATLAS"

2014 AFRL Challenge 16 April 2014

AGGIES THAT LIFT ARMORED VEHICLES



Overview



- Challenge
- Team
- ATLAS Solution
- Conclusion



Challenge



Lift aircraft, and armored vehicles ~45k lbs on uneven and sloping, wet, slippery, muddy, rocky, sandy terrain to extricate equipment and personnel.

The lift kit must be able to create a rescue corridor of 22+ inch height having a secondary function of shoring to hold the load in place.

System should be lightweight and packable to be carried and operated by a single person.





africhallenge.org

3

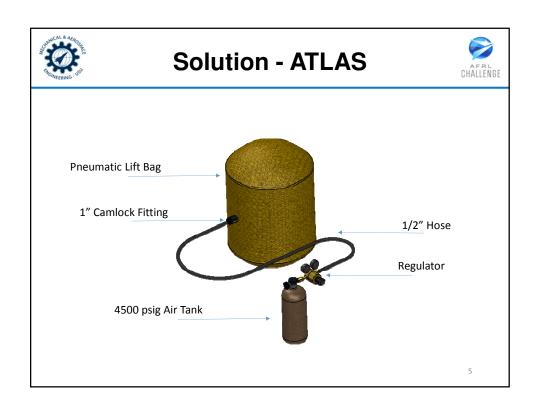


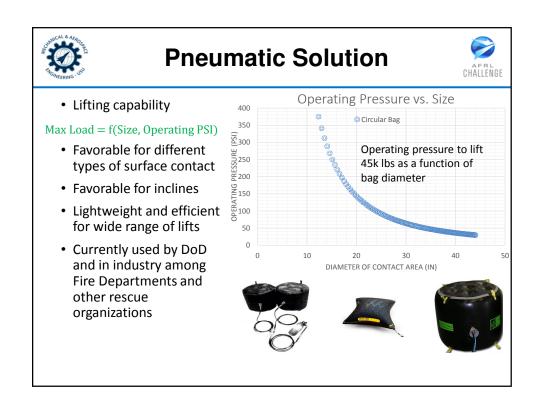
Team

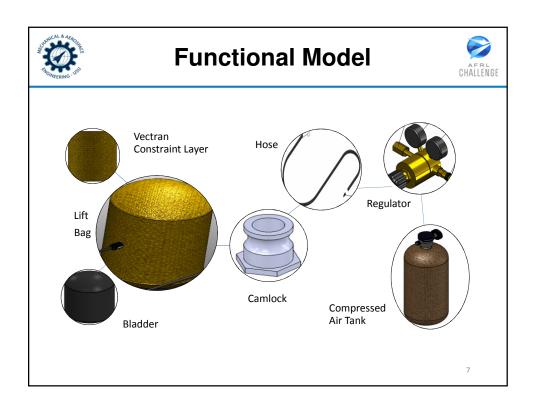


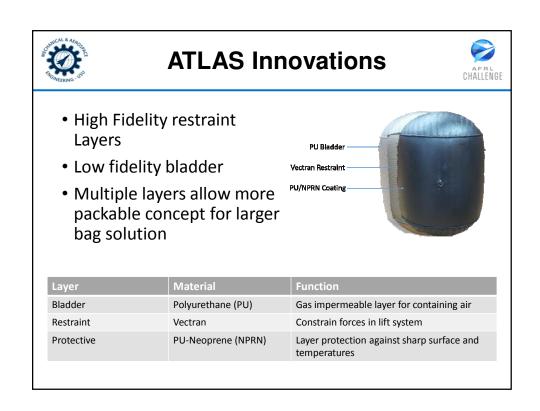


Top L-R: Chase Crandall, Dallan Webb, Philip Le Goubin, Nathan Hawkes, Logan Williams Bottom: Jacob Singleton, Trevor Christensen, Joseph A. Landon, Andrew Gerber, Landon Nielsen











Testing & Development



- Vehicle loads >30,000lbs
- Lifting heights 24 in
- Minimum insertion area <3 in
- Inflation/Deflation
- Inclined surfaces
- Lifting configurations
- Vehicle contact areas
- Uneven & soil surfaces





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Testing & Development



- Challenges & Lessons Learned
 - Co2
 - Stability
 - Deflation time
 - Safety









Improvements & Current Design



- Camlock inflation fitting
 - 1 in ID
 - Full inflation ~1 minute
 - Deflation <30 Seconds
- 2 tested configurations for lift
 - Vertical reaches 24 inches
 - Horizontal reaches 18-20 inches
- 4 Layers of Vectran with DSP sleeve for Camlock fitting



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Requirements Summary



Against USAF System

Against Requirements 20% Lift Height 20" Max Load 45,000 lbs 10,000 lbs 34,000 lbs (SF=2) -24.4% 240% System Weight <30 lbs 21.5 lbs 36 lbs -20% -68.4% 8x10x27" 14x12x22" -71% Packed 12x12x6" -328% Dimensions Operating <150 PSI 27 PSI 75 PSI NA Min Lift Height <3" 33% 33% (Empty)

^{*}Current Best Estimate

^{**}Margin%= [Requirement-Specification]/Requirement*100



Future Design Path



- · Limits removed from schedule and budget
 - Optimize bag diameter to pressure specifications
 - Optimize inflation stem and hose hardware
 - Trade more materials for bladder and protective layers
 - Reduce inflations system weight by 50%
- Development and Design Focus
 - Approach inflation different then HPA
 - Venturi concept or chemicals



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Conclusion



- ATLAS introduces an new concept to pneumatic heavy lift devices with a major improvement in lifting load and height capabilities
- Students from USU have demonstrated the use of their system on inclined slopes and with a variety of heavy vehicle equipment with fast operating times
- Next step design can improve overall size and weight budgets by >30%



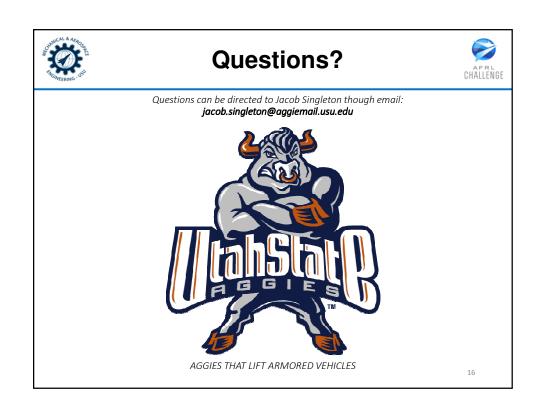


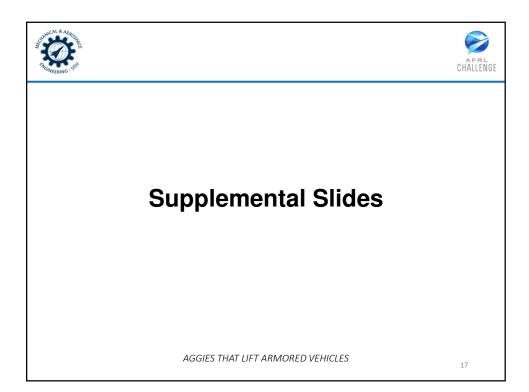


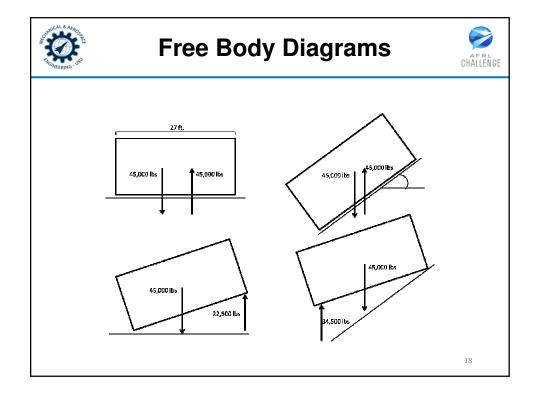
Summary

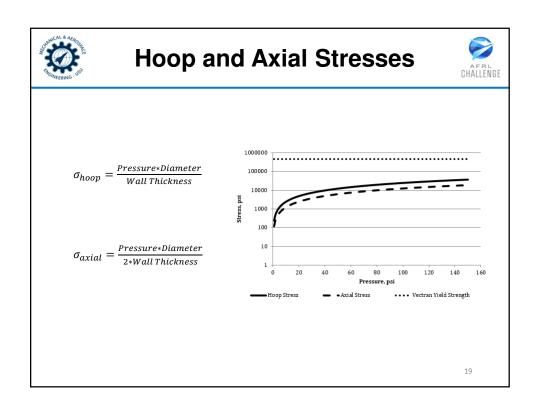


- Challenge
- Team
- ATLAS Solution
 - Design
 - Testing & Lessons Learned
 - Current System Design & Operation
- Conclusion
 - ATLAS and requirements summary
 - Plans for further development

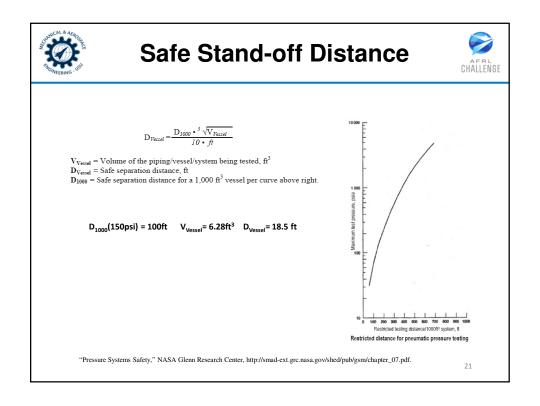


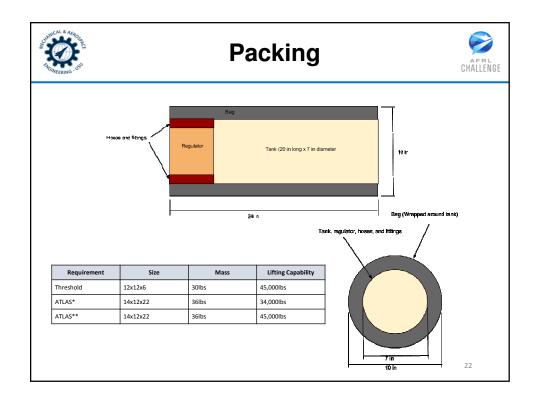














USAF Current System



• Lift Capacity: 10,000lbs

• Lift Height: 20"

• System Weight: <22lbs

• Op. Pressure: 27 PSI

• Packed Dimensions: 8x10x27"





So Haz	zard	Cause	Effect	RPC	Countermeasures	RPC After
Ove	er pressurize air bag	Regulator fails	Load falls and injures rescue personnel	1	Use a pressure gage to test. Regulator incorporates to pressure gauges; one for the tank pressure and one for the output line pressure to the bag. Never lift without shoring if load is smaller than allowable contact area.	3
Ove	er pressurize air bag	Regulator fails	Personnel in blast radius of bag are injured by flying debris	1	Safety margin achieved with robust regulator (5000 psig). Tank is never filled beyond 4500 psig. Personnel will either stand off at safe distance (>18ft) or take cover behind blast shield.	3
Ove		Doesn't unfold properly	Possibility of overpressurinzing the bag	2	Pre packaging folding with "parachute concept." Use a slower inflation time to reduce the risk of bursting the bladder. Also, inflate as much as possible prior to taking load weight.	3
Tan	nk Explosion	Overheat	Personnel in blast radius of bag are injured by flying debris	2	insulate pressurized tank. House the tank in a package with the lift bag when not in operations and leave in backpack to avoid overhearting. Light colored composite SCBA tank to assist in avoiding high temperatures.	3
Bag	g Puncture	Sharp Exposed Edges	Load falls and injures rescue personnel	2	Use sand bag placement to protect bag from sharp edges.Place sandbags under load for shoring during lift. If the bag is punctured the load will only fall down on the sandbags. Polyurethane/Neoprene protective coating applied to restrain layer for protection. Pre and post mission inspections for bag defects.	3
Bag	g Puncture	Sharp Exposed Edges	Personnel in blast radius of bag are injured by flying debris	2	Use sand bag placement to protect bag from sharp edges. Only inflate from safe stand-off distance (>18ft). Polyurethane/Neoprene protective coating applied to restrain layer for protection. Pre and post mission inspections for bag defects.	3
Sta	bility	Slips out from under vehicle	Load falls and injures rescue personnel	2	This will allow for more stable lifting on different inlinces and types of surfaces that may be more slippery. Tow straps assist in vehicle and bag stability.	3
Sab	bility	Bad bag placement	Load falls and injures rescue personnel	1	Inflate bag slowly, and closely monitor the positioning of the vehicle. If it appears unstable. Deflate and try again. "Lift an inch, shore an inch"	3
Air	Fittings	Bent or broken	Unable to inflate bag and perform rescue operation	2	Pre and post mission inspections. Make sure the system is fully functional before leaving.	3
Hos	se	Bursts	Unable to inflate bag and perform rescue operation	2	Use anti burst tape or FIBERFIX to repair leak fo operations.	3